

Ref #	Hits	Search Query	DBs	Default Operator	Plurals	Time Stamp
L1	26	(multiaxes or robot) position computer work calibration	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	SAME	ON	2005/12/09 11:56
L2	3	(multiaxes or robot) position computer work calibration	US-PGPUB	SAME	ON	2005/12/09 11:56
L3	715	(multiaxes or robot) position computer work calibration	US-PGPUB	AND	ON	2005/12/09 11:57
L4	98	(multiaxes or robot) position computer work calibration poses	US-PGPUB	AND	ON	2005/12/09 11:57
L5	85	(multiaxes or robot) position computer work calibration poses coordinates	US-PGPUB	AND	ON	2005/12/09 11:58